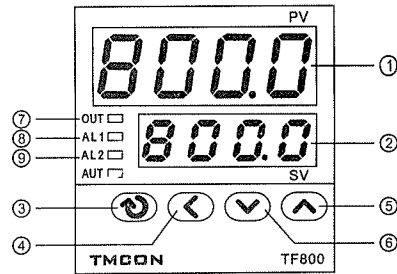
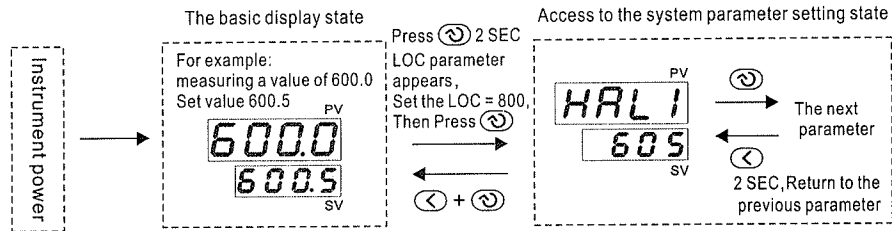


5. Panel Description

- ① Upper display window
- ② Lower display window
- ③ To the parameter key, the Enter key
- ④ Data shift key
- ⑤ Increase the key
- ⑥ Reduce the key
- ⑦ OUT Lamp
- ⑧ AL1 Lamp
- ⑨ AL2 Lamp



6. Display the status and basic operation



6.1. System parameter setting

In the basic display state, press and hold (3) key 2 seconds, LOC parameter appears, set the LOC = 800, Then press the (3) button to confirm and enter the system parameter setting state. (4), (5), (6) Key can directly modify the parameter values. Press the (5) key to reducing the data, press the (6) key to increase the data, Waiting to modify the value of the decimal point will flash (like a cursor), press key and hold, you can quickly increase / decrease in value, And the speed will be automatically accelerated. also press the (4) key to move to modify the data location (cursor), the operation is more efficient. (3) Key can be stored to modify parameter values and display the next parameter, press and hold (4) key 2 seconds, and can return to the previous parameter; press and hold (4) key and then press the (3) key can immediately exit the parameter setting state.

6.2 Set Value Setting

In basal display status, if the parameter lock "Loc" isn't locked, we can set setpoint (SV) by pressing (4) first. then can press (4), (5) or (6) to adjust value. Press (5) key to decrease the value, (6) key to increase the value, and (4) key to move to the digit expected to modify. Keep pressing (5) or (6), the speed of decreasing or inscreasing value get quick. The range of setpoint is between the parameter SPL and SPH.

6.3 "At"PID Parameter auto-tuning

"At" parameter "OFF" is set to "ON" and then press the (3) KEY to confirm instrument can start the implementation of the auto-tuning Given function, the instrument in the basic display state display will flash the word "At", the instrument after 2 oscillation cycle ON-OFF control can automatically calculate the PID parameters. If you want to advance to give up auto-tuning, "At" parameter "ON" is set to "OFF" and then press (3) key to confirm. Given tuning parameter values obtained are not identical, to perform auto-tuning function, should be first given value set in The most commonly used value or middle value, if the system is good insulation properties of the furnace, the given value should be set in the system uses the maximum, and then Execute the start of the operation of auto-tuning function. Reasons to learn, auto-tuning after the initial use, the effect may not be the best, you need a period of time (usually the same time auto-tuning control) before they can get the best results.

7. Parameter list and function

press and hold (3) key 2 seconds, LOC parameter appears, set the LOC = 800, Then press the (3) key to confirm and enter the system parameter setting state.

| Parameter code | Meaning of parameters | Explain | Setting range |
|----------------|------------------------------------|---|-------------------|
| LOC | Parameter lock | LOC<9000, will automatically for 0, allowed to modify the SV Set Value. LOC≥9000, are not allowed to modify the SV Set Value. Set the LOC = 800, then press (3) key to confirm, can enter the following system parameters. | 0~9999 |
| HAL1 | AL1 high limit alarm value | "HAL1" is the absolute value alarm or deviation value alarm, by "ALtd" parameter definition. When the value set to Max. will disable this function.(3200) | -999~ +32000 |
| LAL1 | AL1 low limit alarm value | "LAL1" is the absolute value alarm or deviation value alarm, by "ALtd" parameter definition. When the value set to Min. will disable this function.(-999) | |
| HAL2 | AL2 high limit alarm value | "HAL1" is the absolute value alarm or deviation value alarm, by "ALtd" parameter definition. When the value set to Max. will disable this function.(3200) | |
| LAL2 | AL2 low limit alarm value | "LAL1" is the absolute value alarm or deviation value alarm, by "ALtd" parameter definition. When the value set to Min. will disable this function.(-999) | |
| At | auto-tuning | OFF: close the auto-tuning function. ON: start a auto-tuning function. auto-tuning finish will automatically returns to the OFF state. | ON OFF |
| AHYS | Alarm hysteresis | Avoid frequent alarm on-off action because of the fluctuation of PV | 0~2000 |
| ALtd | Alarm mode | ALtd=0, AL1 is the deviation value alarm, AL2 is the absolute value alarm. ALtd=1, AL1 and AL2 is the absolute value alarm. ALtd=2, AL1 and AL2 is the deviation value alarm. | 0~2 |
| CntL | Control mode | onoF: on-off control. For situation not requiring high precision. FPId: advanced artificial intelligence "FUZZY PID" control. | onoF FPId |
| orEv | Selection of heating refrigeration | onr: Reverse acting. Increase in measured variable causes a decrease in the output, such as heating control. ond: Direct acting. Increase in measured variable causes an increase in the output, such as refrigerating control. | onr ond |
| P | Proportional band | Proportional band in PID and APID control. Instead of percentage of the measurement range, the unit is the same as PV. Generally, optimal P, I, D and CP can obtained by auto tuning. They can also be manually inputted if you already know the correct values. | 1~32000 |
| I | Integration time | No integral effect when I=0 | 1~9999 seconds |

| | | | |
|-----|----------------------------|---|----------------|
| d | Differential time | No derivative effect when d=0 | 0~3200 seconds |
| CP | Control cycle | CP reflect the instrument operator to adjust the speed, the size of the CP that affect the control accuracy. With SSR, SCR output control cycle preferable to shorter, usually 0.5-3.0 Seconds. The relay switch output is generally in 15-40 seconds. When the output relay switches , the CP will be limited to 3 seconds, And self-tuning At will automatically set the CP as the appropriate value, taking into account the control accuracy And mechanical switch life. When the control mode CntL = onOF, the action of the CP as an output disconnect or power-on output ON Delay time. | 0.2~300.0 |
| HYS | Control hysteresis | HYS is used for on-off control to avoid frequent on-off action of relay. For a reverse acting (heating) system, when PV > SV, output turns off; when PV<SV-HYS, output turns on. For a direct acting (cooling) system, when PV<SV, output turns off; when PV>SV+HYS, output turns on. | 0~2000 |
| Int | Input Signal | Input spec: K, E, J, N, Pt (Pt100) | |
| dp | Decimal point | 0 (no decimal), 0.0 (one decimal place). | 0 0.0 |
| SC | Input Shift Adjustment | Sc is used to shift input to compensate the error caused by transducer, input signal, or auto cold junction compensation of thermocouple. PV after compensation=PV before compensation + Sc It is generally set to 0. The incorrect setting will cause measurement inaccurate. | -1999~+4000 |
| InF | PV input filter | The value of InF will determine the ability of filtering noise. When a large value is set, the measurement input is stabilized but the response speed is slow. Generally, it can be set to 1 to 3. If great interference exists, then you can increase parameter "InF" gradually to make momentary fluctuation of measured value less than 2 to 5. When the instrument is being metrological verified, "InF" s can be set to 0 or 1 to shorten the response time. | 0~40 |
| dU | Temperature unit selection | °C: celsius equals °F: fahrenheit equals | °C °F |
| SvL | Low limit of SV | Minimum value that SV is allowed to be. | -9990~+30000 |
| SvH | Upper limit of SV | Maximum value that SV is allowed to be. | |

8、 Note

(1) Can not normally display measured values in the display window alternating show: "orAL" character, indicating that the input of the measurement signal abnormalities or Out of range; check Int parameter settings, and then the input sensor signals are the same category, if it is determined the same, check the input sensing Signal not pick the wrong line, if it is determined to not pick the wrong line, check whether the sensor problem, replace another sensor to try.

(2) The instrument used by the local environmental temperature and humidity can not exceed the scope of the provisions, the instrument around should allow sufficient space for heat dissipation, instrument internal temperature rise due to thermal radiation will lead to a result of the measurement accuracy and service life of the affected. In this Case, to be taken to a forced cooling fan or other measures to reduce the ambient temperature.

(3) the extension or connection then the thermocouple leads should be used with the thermocouple type to match the compensation conductor; extend or connect the thermoelectric Resistance of the lead, you should use the minimal resistance of the wire and cable away from power lines and load connection, in order to avoid signal interference.

9、 default settings.

| Parameter code | factory setting | Parameter code | factory setting | Parameter code | factory setting |
|------------------|-----------------|----------------|-----------------|----------------|-----------------|
| L _{oc} | 0 | CntL | FPI d | dP | 00 |
| H _{AL1} | 3200 | orEu | onr | Sc | 00 |
| L _{AL1} | -999 | P | 250 | InF | 2 |
| H _{AL2} | 3200 | I | 200 | dU | °C |
| L _{AL2} | -999 | d | 500 | SvL | -999 |
| At | oFF | CP* | | SvH | 3200 |
| AHYS | 20 | HYS | 20 | | |
| ALtd | 0 | Int | μ | | |

* solid state relay output type CP factory is set to 20 ,
the relay contact output type CP factory set to 150 .



Read this manual before using, to prevent the error operation caused by the failure to Fully understand the operating procedures, and retain the manual for ready reference.